

# Maximum Likelihood Methods in Molecular Phylogeny

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# Main Types of Phylogenetic Methods

Data	Method	Evaluation Criterion
Characters (Alignment)	<b>Maximum Parsimony</b>	Parsimony
	<b>Statistical Approaches: Likelihood, Bayesian</b>	Evolutionary Models
Distances	<b>Distance Methods</b>	

# Introduction: ML on Coin Tossing

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## Probability

$p(k \text{ heads in } n \text{ tosses} | \theta)$

**Aim:** The ML approach searches for that parameter set  $\theta$  for the generating process which maximizes the probability of our given data.

Hence, "*likelihood flips the probability around.*"

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**Probability**

**Likelihood**

$$p(k \text{ heads in } n \text{ tosses} | \theta) \equiv L(\theta | k \text{ heads in } n \text{ tosses})$$

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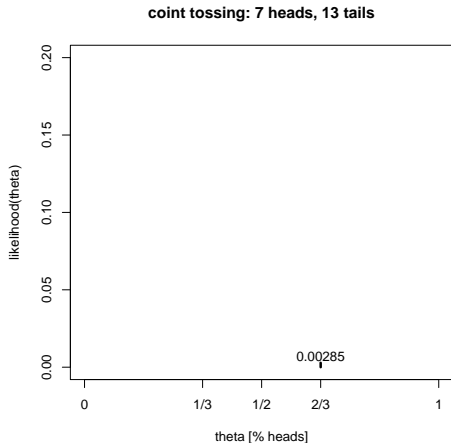
$$= \binom{n}{k} \theta^k (1 - \theta)^{n-k}$$

(here binomial distribution)

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# Introduction: ML on Coin Tossing (Estimate)



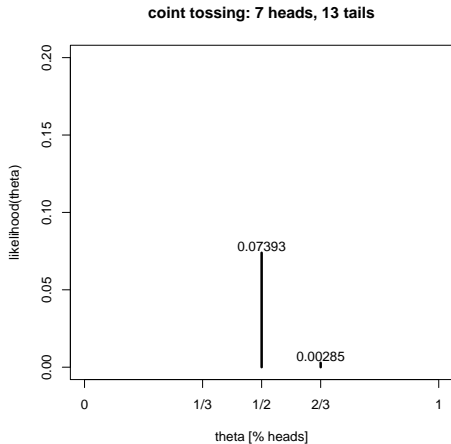
## Three coin case

$$L(\theta|7 \text{ heads in } 20) = \binom{20}{7} \theta^7 (1-\theta)^{13}$$

for each coin  $\theta \in \{\frac{1}{3}, \frac{1}{2}, \frac{2}{3}\}$



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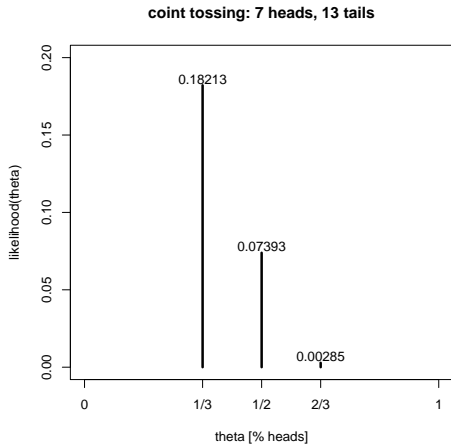


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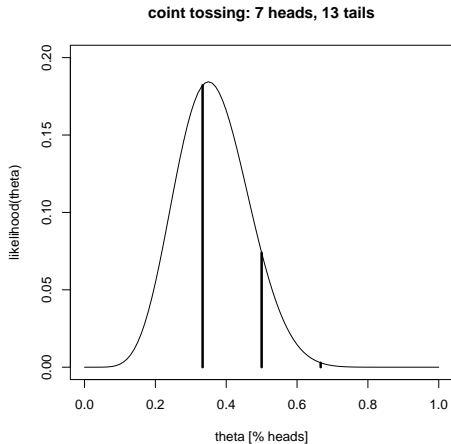


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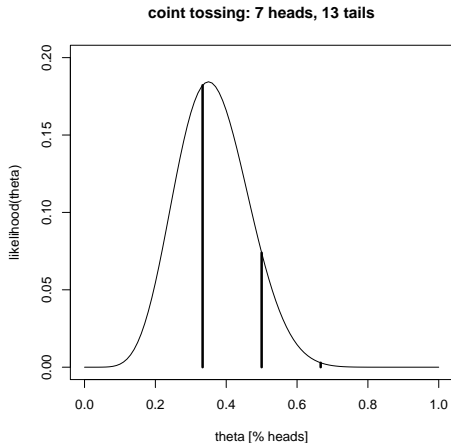
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ML estimate:  $L(\hat{\theta}) = 0.1844$  where  
coin shows  $\hat{\theta} = 0.35$  heads

# From Coins to Phylogenies?

While the coin tossing example might look easy, in phylogenetic analysis, the parameter (set)  $\theta$  comprises:

- evolutionary model
- its parameters
- tree topology
- its branch lengths

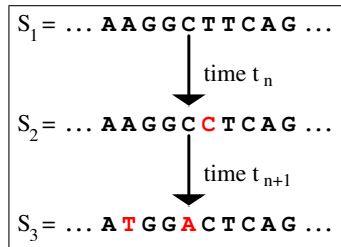
That means, a **high dimensional optimization problem**.

Hence, some parameters are often estimated/set separately.

- Evolution is usually modeled as a  
  
stationary, time-reversible Markov process.
- What does that mean?

## Markov Process

The (evolutionary) process evolves **without memory**, i.e. sequence  $S_2$  mutates to  $S_3$  during time  $t_{n+1}$  independent of state of  $S_1$ .



## Stationary:

The overall character frequencies  $\pi_j$  of the nucleotides or amino acids are in an **equilibrium** and remain constant.

## Time-Reversible:

Mutations in either direction are equally likely

$$\pi_i \cdot P_{ij}(t) = P_{ji}(t) \cdot \pi_j$$

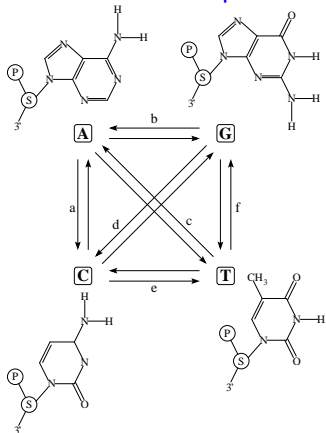
This means a mutation is as likely as its back mutation.

$$P(i \rightarrow j) = P(i \leftarrow j) \quad (\text{JC69})$$



# Substitution Models

Evolutionary models are often described using a **substitution rate matrix**  $R$  and **character frequencies**  $\Pi$ . Here,  $4 \times 4$  matrix for DNA models:



$$R = \begin{pmatrix} A & C & G & T \\ - & a & b & c \\ a & - & d & e \\ b & d & - & f \\ c & e & f & - \end{pmatrix}$$

$$\Pi = (\pi_A, \pi_C, \pi_G, \pi_T)$$

# From Substitution rates to probabilities

...  $R$  and  $\Pi$  are combined into the **instantaneous rate matrix  $Q$**

$$Q = \begin{pmatrix} \bullet_A & a\pi_C & b\pi_G & c\pi_T \\ a\pi_A & \bullet_C & d\pi_G & e\pi_T \\ b\pi_A & d\pi_C & \bullet_G & f\pi_T \\ c\pi_A & e\pi_C & f\pi_G & \bullet_T \end{pmatrix} \quad \begin{aligned} \bullet_A &= -(a\pi_C + b\pi_G + c\pi_T) \\ \bullet_C &= -(a\pi_A + d\pi_G + e\pi_T) \\ \bullet_G &= -(b\pi_A + d\pi_C + f\pi_T) \\ \bullet_T &= -(c\pi_A + e\pi_C + f\pi_G) \end{aligned}$$

(where the row sums are zero).

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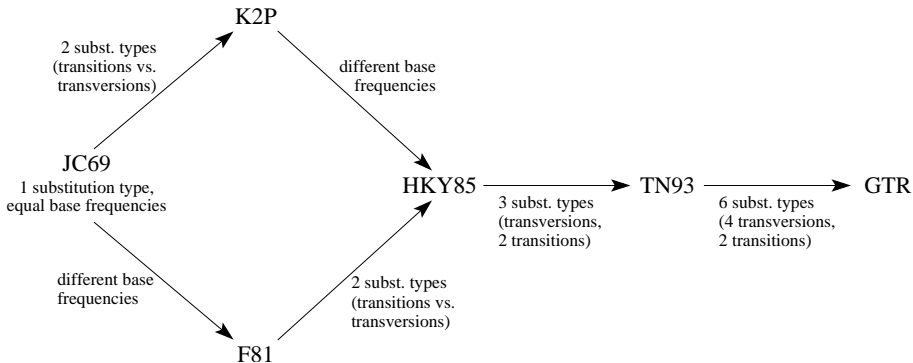
(where the row sums are zero).

Given now the instantaneous rate matrix  $Q$ , we can compute a substitution **probability matrix  $P$**

$$P(t) = e^{Qt}$$

With this matrix  $P$  we can compute the **probability  $P_{ij}(t)$**  of a change  $i \rightarrow j$  over a time  $t$ .

# Relations between DNA models



Generally this is the same for protein sequences, but with  $20 \times 20$  matrices. Some protein models are:

- Poisson model ("JC69" for proteins)
- Dayhoff (Dayhoff *et al.*, 1978)
- JTT (Jones *et al.*, 1992)
- mtREV (Adachi & Hasegawa, 1996)
- cpREV (Adachi *et al.*, 2000)
- VT (Müller & Vingron, 2000)
- WAG (Whelan & Goldman, 2000)
- BLOSUM 62 (Henikoff & Henikoff, 1992)

## Computing ML Distances Using $\mathbf{P}_{ij}(t)$

The Likelihood of sequence  $s$  evolving to  $s'$  in time  $t$ :

$$L(t|s \rightarrow s') = \prod_{i=1}^m \left( \pi(s_i) \cdot P_{s_i s'_i}(t) \right)$$

Likelihood surface for two sequences under JC69:

GATCCTGAGAGAAATAAAC

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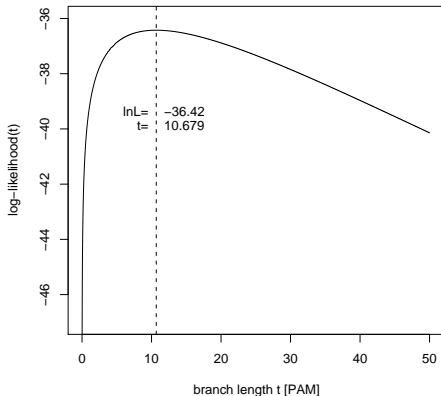
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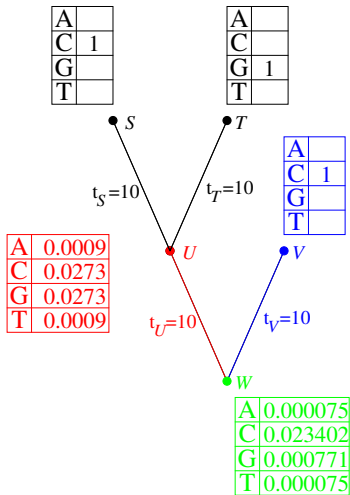
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Note: we do not compute the probability of the distance  $t$  but that of the data  $D = \{s, s'\}$ .



# Likelihoods of Trees (Single column $\begin{matrix} C \\ G \\ C \end{matrix}$ , given tree)

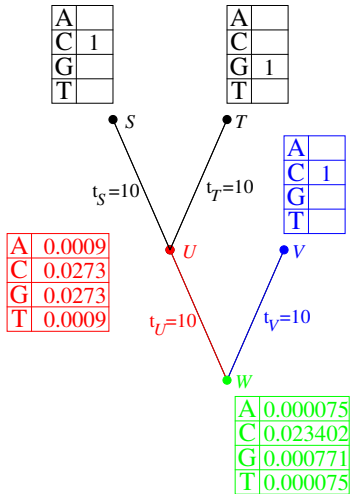


Likelihoods of nucleotides at inner nodes:

$$L_U(i) = [P_{iC}(10) \cdot L(C)] \cdot [P_{iG}(10) \cdot L(G)]$$



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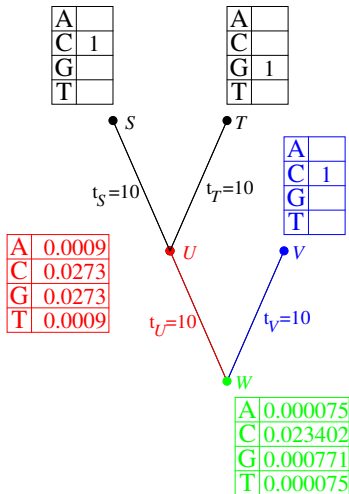
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$$L_W(i) = \left[ \sum_{u=ACGT} P_{iu}(t_U) \cdot L_U(u) \right] \cdot$$

$$\left[ \sum_{v=ACGT} P_{iv}(t_V) \cdot L_V(v) \right]$$

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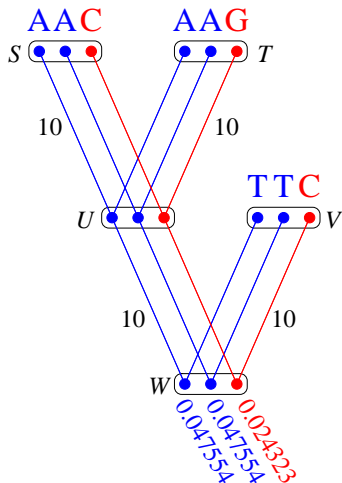
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Site-Likelihood of an alignment column  $k$ :

$$L^{(k)} = \sum_{i=\substack{A \\ C \\ G \\ T}} \pi_i \cdot L_W(i) = 0.024323$$



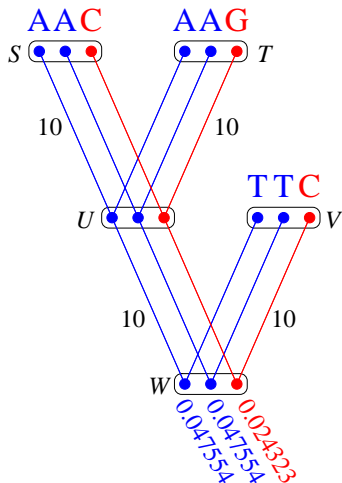
# Likelihoods of Trees (multiple columns)



Considering this tree with  $n = 3$  sequences of length  $m = 3$  the tree likelihood of this tree is

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or the log-likelihood

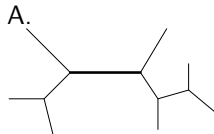
$$\ln \mathcal{L}(T) = \sum_{k=1}^m \ln L^{(k)} = -9.80811$$

# Adjusting Branch Lengths Step-By-Step

To compute optimal branch lengths do the following. Initialize the branch lengths.

Choose a branch (A.). Move the virtual root to an adjacent node (B.).

Compute all partial likelihoods recursively (C.). Adjust the branch length to maximize the likelihood value (D.).

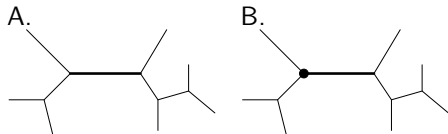


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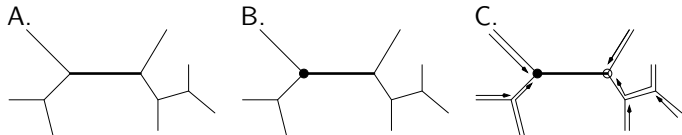


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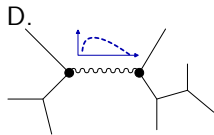
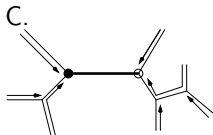
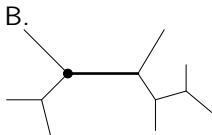
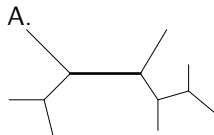


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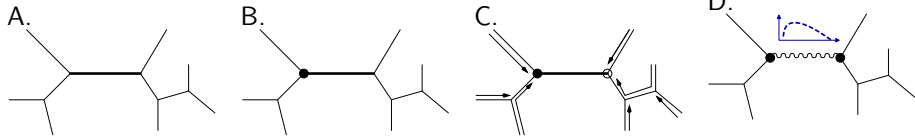


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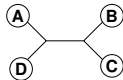
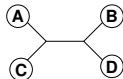
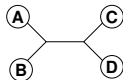


Repeat this for every branch until no better likelihood is gained.

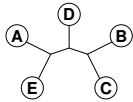
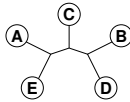
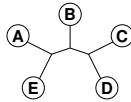
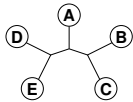
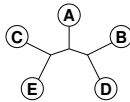
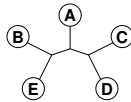
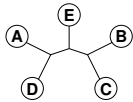
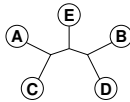
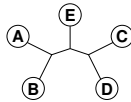
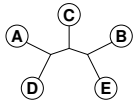
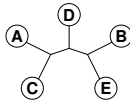
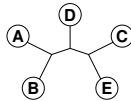
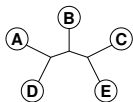
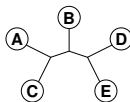
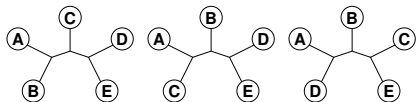
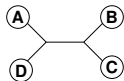
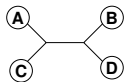
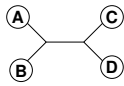
# Number of Trees to Examine...



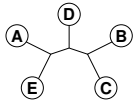
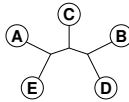
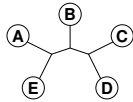
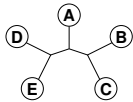
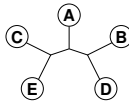
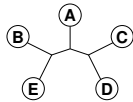
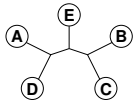
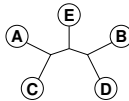
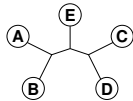
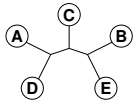
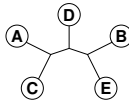
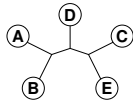
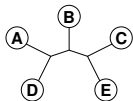
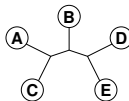
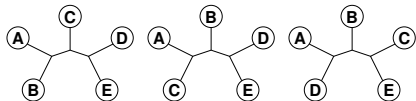
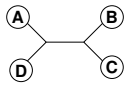
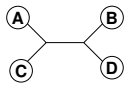
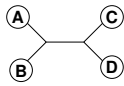
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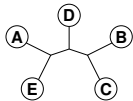
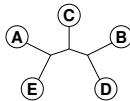
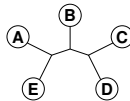
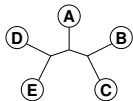
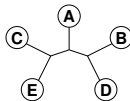
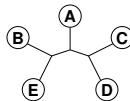
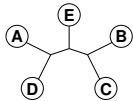
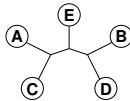
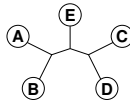
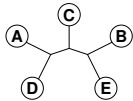
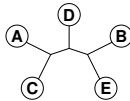
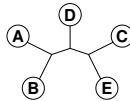
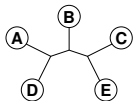
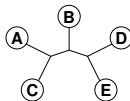
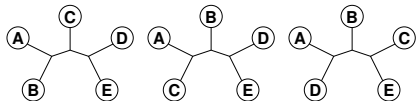
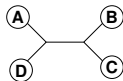
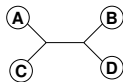
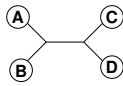


# Number of Trees to Examine...



$$B(n) = \frac{(2n-5)!}{2^{n-3}(n-3)!}$$

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$$B(10) = 2027025$$

$$B(55) = 2.98 \cdot 10^{84}$$

$$B(100) = 1.70 \cdot 10^{182}$$

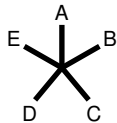
**Exhaustive Search:** guarantees to find the optimal tree, because all trees are evaluated, but not feasible for more than 10-12 taxa.



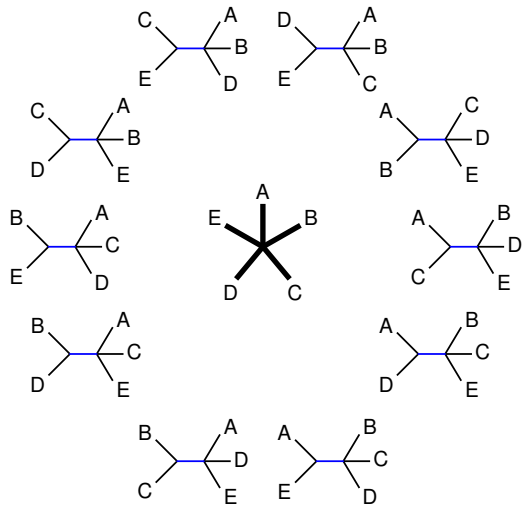
- Exhaustive Search:** guarantees to find the optimal tree, because all trees are evaluated, but not feasible for more than 10-12 taxa.
- Branch and Bound:** guarantees to find the optimal tree, without searching certain parts of the tree space – can run on more sequences, but often not for current-day datasets.

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- Branch and Bound:** guarantees to find the optimal tree, without searching certain parts of the tree space – can run on more sequences, but often not for current-day datasets.
- Heuristics:** cannot guarantee to find the optimal tree, but are at least able to analyze large datasets.

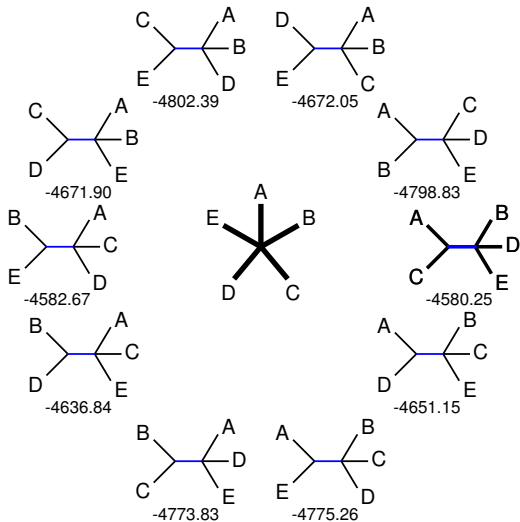
# Build up a tree: Star Decomposition



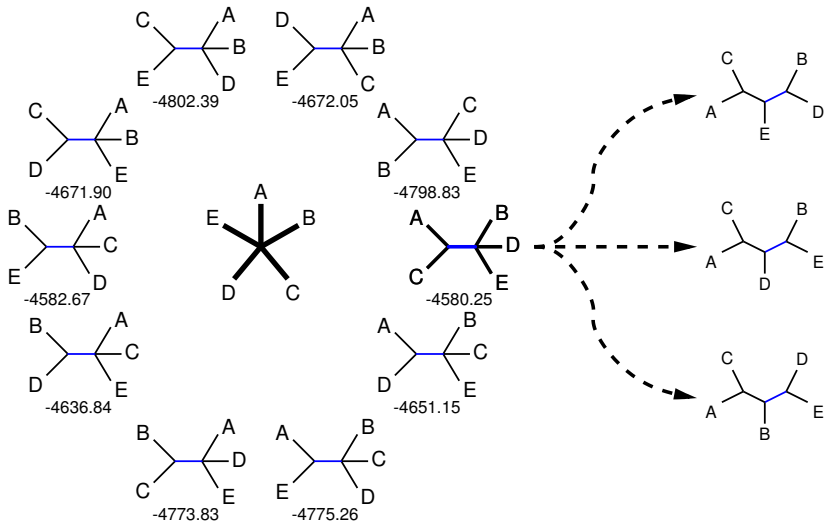
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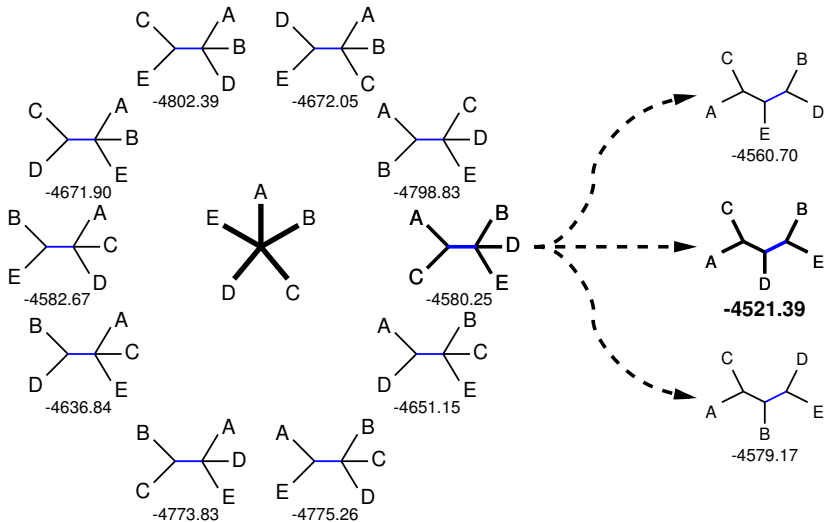
# Build up a tree: Star Decomposition



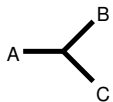
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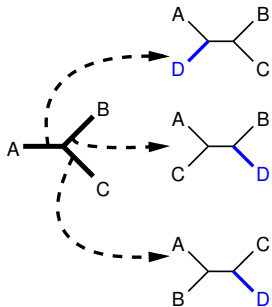


# Build up a tree: Stepwise Insertion

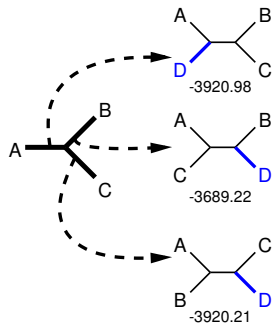




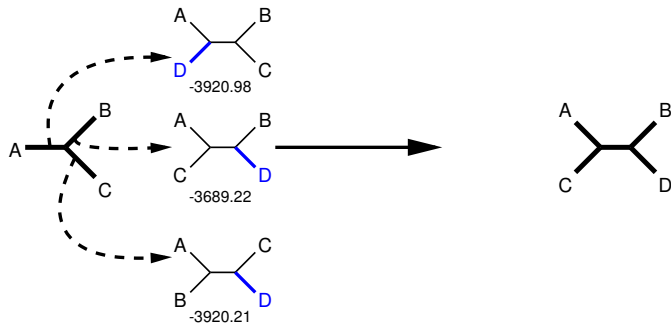
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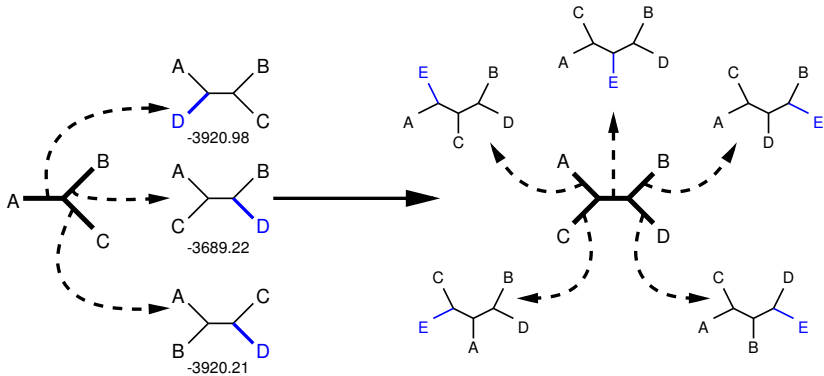
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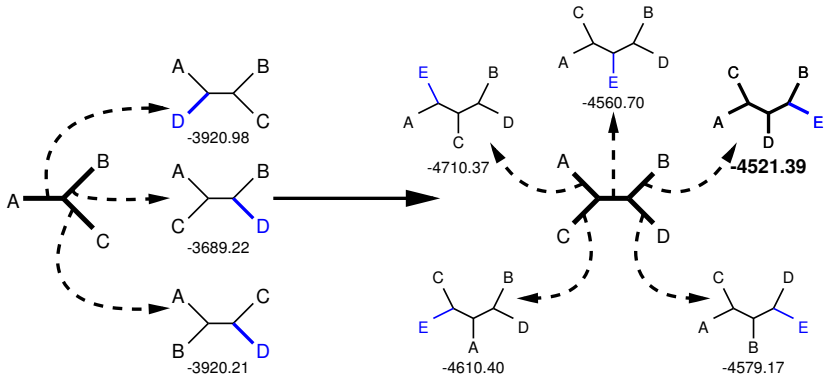
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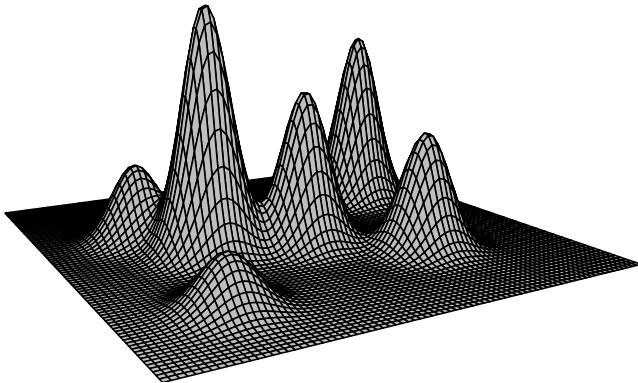


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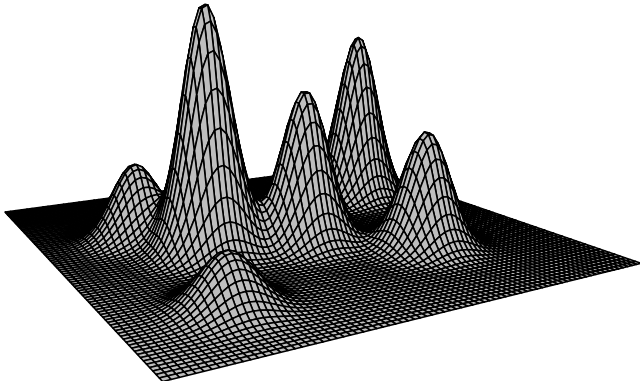
# Local Maxima

What if we have **multiple maxima** in the likelihood surface?



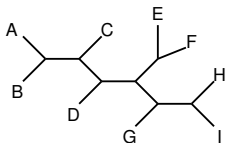
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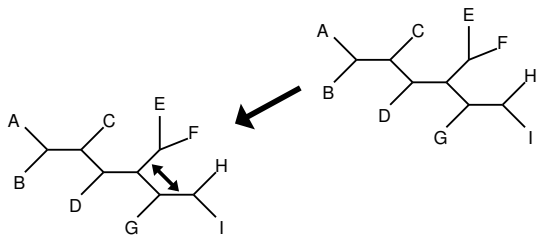
**Tree rearrangements** to escape local maxima.

# Tree Rearrangements: Scanning a Tree's Neighborhood

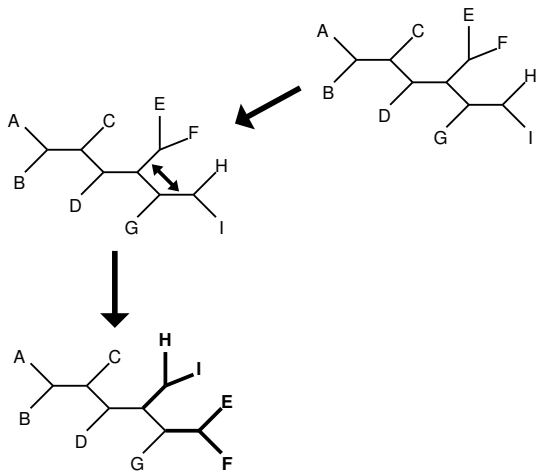




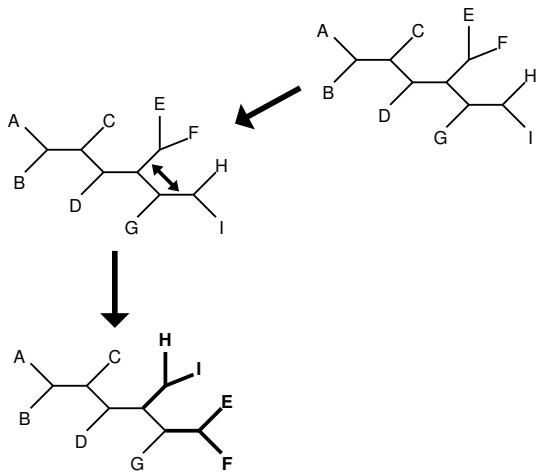
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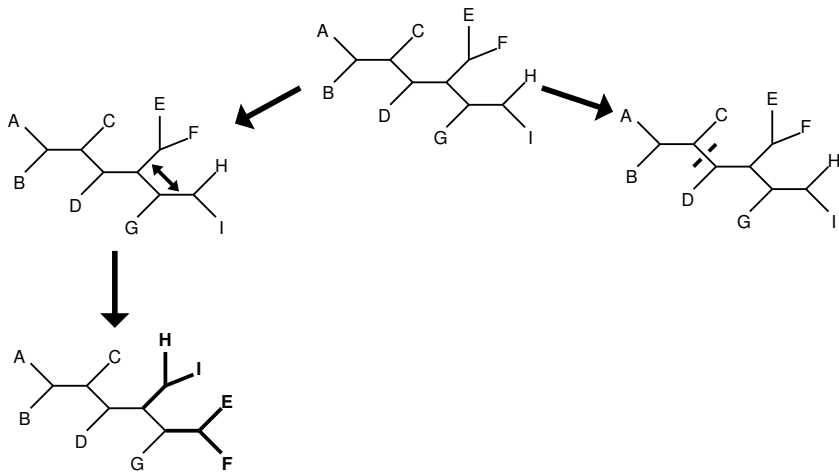
# Tree Rearrangements: Scanning a Tree's Neighborhood



## Nearest Neighbor Interchange

Possible NNI trees =  $O(n)$

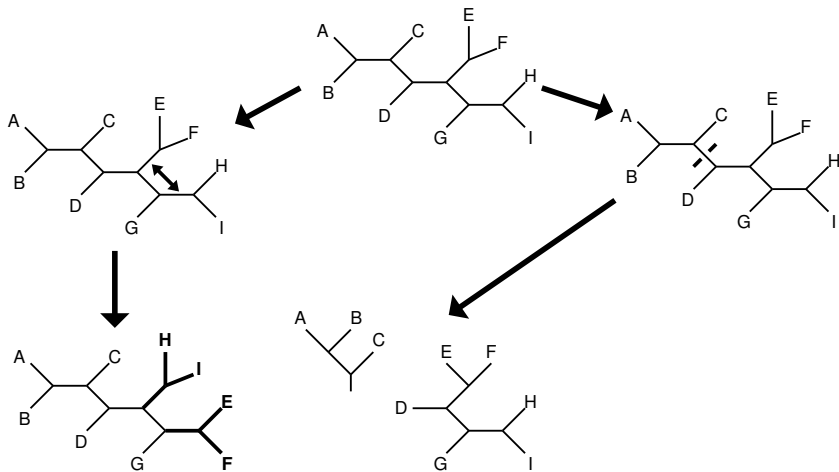
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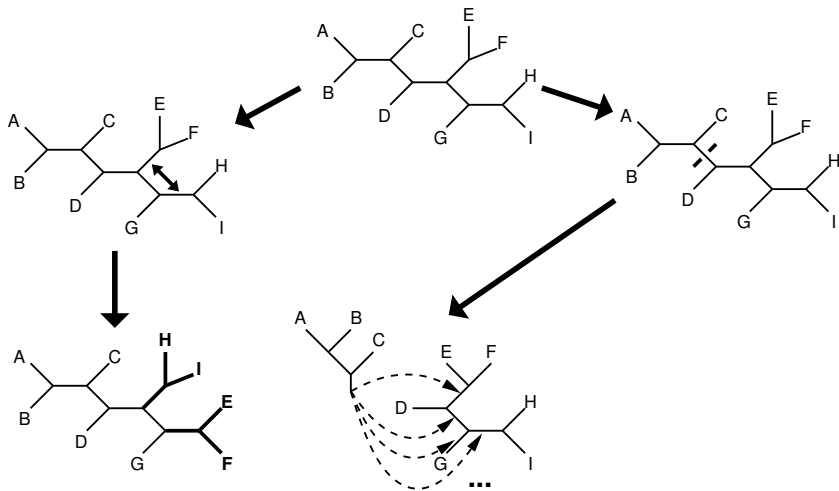
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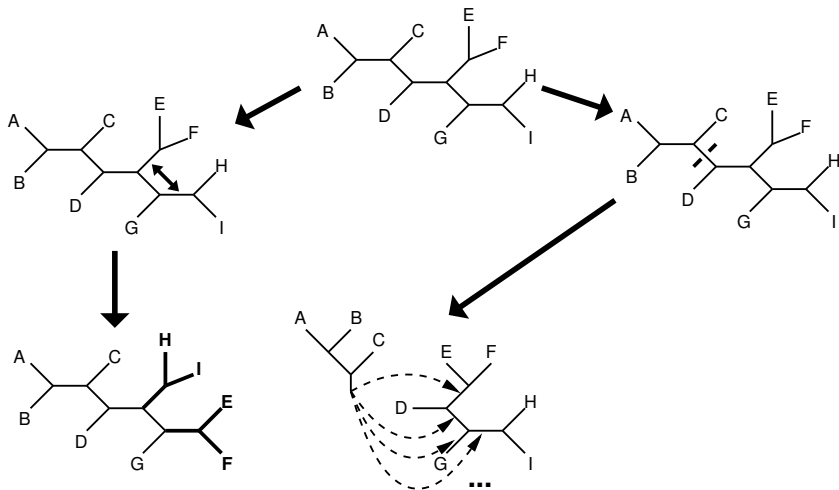
# Tree Rearrangements: Scanning a Tree's Neighborhood



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# Tree Rearrangements: Scanning a Tree's Neighborhood



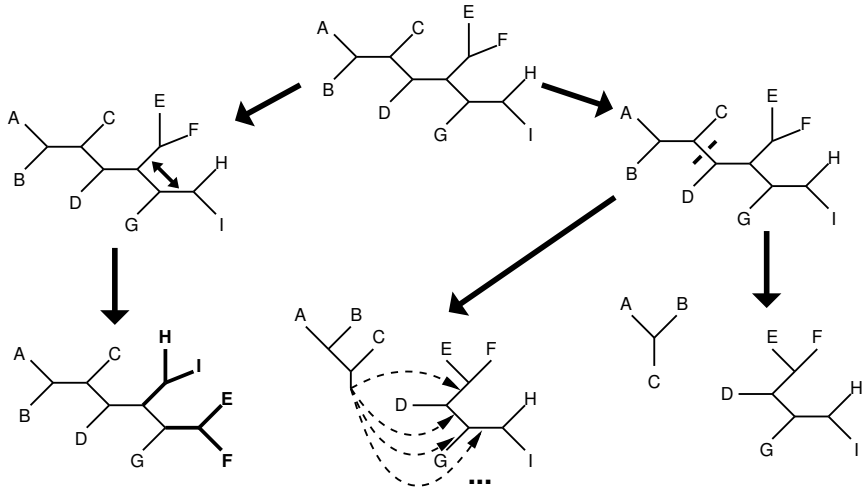
**Nearest Neighbor Interchange**

Possible NNI trees =  $O(n)$

**subtree pruning + regrafting**

Possible SPR trees =  $O(n^2)$

# Tree Rearrangements: Scanning a Tree's Neighborhood



**Nearest Neighbor Interchange**

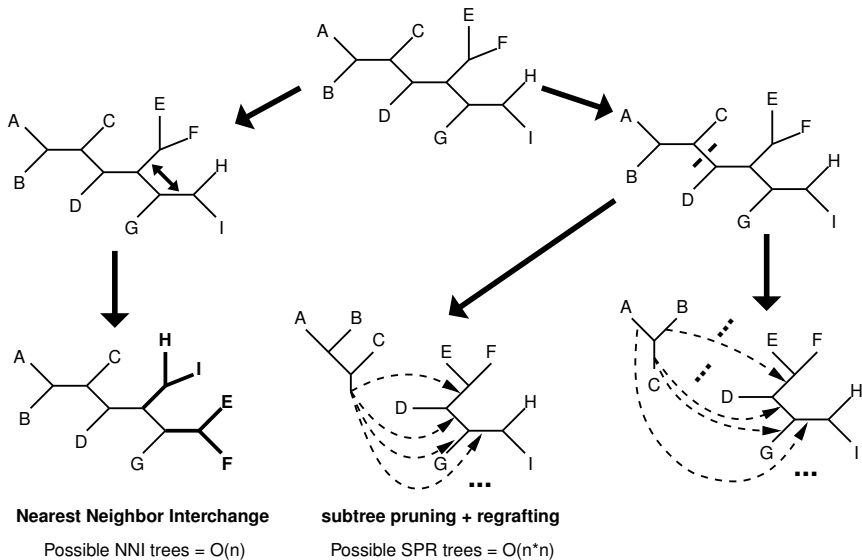
Possible NNI trees =  $O(n)$

**subtree pruning + regrafting**

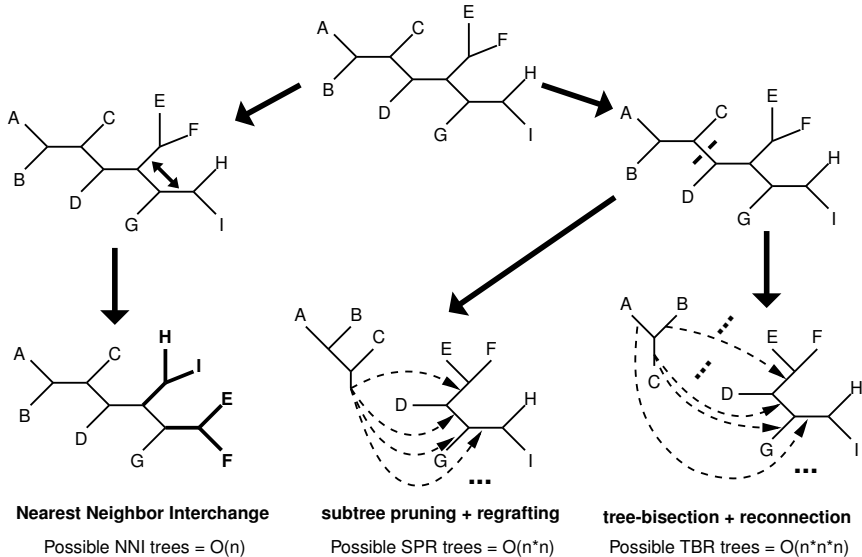
Possible SPR trees =  $O(n^2)$



# Tree Rearrangements: Scanning a Tree's Neighborhood



# Tree Rearrangements: Scanning a Tree's Neighborhood



## Concept: Stepwise insertion + NNI/SPR

- 1 Build tree with **stepwise insertion**
  - (a) after each insertion optimize using NNI/local rearrangement (default, but user-adjustable gradually up to SPR; only fastDNAmI)
  - (b) repeat (a) rearrangements until no better tree found.

## Concept: Stepwise insertion + NNI/SPR

- 1 Build tree with **stepwise insertion**
  - (a) after each insertion optimize using NNI/local rearrangement (default, but user-adjustable gradually up to SPR; only fastDNAML)
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- 2 after the last insertion optimize using SPR/global rearrangement (in DNAML; in fastDNAML user-adjustable gradually down to NNI)
- 3 repeat (2) rearrangements until no better tree found.

## Concept: Stepwise insertion + NNI/SPR

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- 3 repeat (2) rearrangements until no better tree found.
  - Pro: Evaluating large neighborhood with SPR.
  - Con: Slow.

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**Pro:** Evaluating large neighborhood with SPR.

**Con:** Slow.

**Note:** To save time, in other methods steps (1) and (2) are usually substituted by swiftly computed trees (e.g., BioNJ).

## Concept: Star decomposition + NNI

- 1 Build tree with [star decomposition](#)
- 2 after the last insertion optimize using NNI/local rearrangement
- 3 repeat rearrangements (2) until no better tree found.

[Con:](#) Slow, not maintained anymore.

## Concept: Star decomposition + NNI

- 1 Build tree with [star decomposition](#)
- 2 after the last insertion optimize using NNI/local rearrangement
- 3 repeat rearrangements (2) until no better tree found.

[Con:](#) Slow, not maintained anymore.



## Concept: MP tree + LSR

Descendant on fastDNAm1, but . . .

- 1 Starting with MP tree.
- 2 Uses *lazy subtree rearrangements* (only the 3 insertion branches are optimized), collecting candidates.
- 3 Candidates are evaluated.
- 4 Iterating (2)-(4).

## Concept: MP tree + LSR

Descendant on fastDNAmI, but . . .

- 1 Starting with MP tree.
- 2 Uses *lazy subtree rearrangements* (only the 3 insertion branches are optimized), collecting candidates.
- 3 Candidates are evaluated.
- 4 Iterating (2)-(4).

**Pro:** Fast,  
smart algorithmic and numerical optimized ML computation.

**Con:** Only few trees fully evaluated trees.

## Concept: BioNJ tree + fastNNI

- 1 Start with BioNJ tree.
- 2 Do fastNNIs to optimize trees, i.e., evaluate all NNIs simultaneously and then merge all best ones which are non-conflicting.
- 3 Repeat (1) until no better tree found anymore.

## Concept: BioNJ tree + fastNNI

- 1 Start with BioNJ tree.
- 2 Do fastNNIs to optimize trees, i.e., evaluate all NNIs simultaneously and then merge all best ones which are non-conflicting.
- 3 Repeat (1) until no better tree found anymore.

Pro: Fast

Con: Prone to get stuck on local optima due to NNI-only.  
(SPR-based version PhyML-SPR has not been released yet.)

- 1 Start with BioNJ tree.
- 2 Evaluate SPR by fast non-ML criterion to find best candidates.
- 3 Evaluate the candidate(s) more rigorously with ML and fastNNI.
- 4 Repeat until no better tree found anymore.

**Pro:** less prone to get stuck on local optima.

**Con:** software not released yet.

## Concept: BioNJ tree + randomization + fastNNI

- 1 Start with BioNJ tree.
- 2 Do fastNNIs to optimize trees, i.e., evaluate all NNIs simultaneously and then accept all best ones which are non-conflicting. (after first round, identical to PHYML).
- 3 Remove randomly a certain amount of taxa and re-insert them by a fast and rough quartet-based method. (some randomization)
- 4 Repeat (2)-(3) until stop criterion is met.

## Concept: BioNJ tree + randomization + fastNNI

- 1 Start with BioNJ tree.
- 2 Do fastNNIs to optimize trees, i.e., evaluate all NNIs simultaneously and then accept all best ones which are non-conflicting. (after first round, identical to PHYML).
- 3 Remove randomly a certain amount of taxa and re-insert them by a fast and rough quartet-based method. (some randomization)
- 4 Repeat (2)-(3) until stop criterion is met.

**Pro:** Can evade local optima,  
offers automatic stopping criterion,  
hints when search didn't run enough,  
numerically optimized ML computation,  
offers codon models

**Con:** slower than PhyML/RAxML

# ML programs: Genetic Algorithms (GARLI, MetaPIGA)

- 1 Start with some (random) tree.
- 2 View tree topology, branch lengths, and model parameter as part of a 'genome'.
- 3 Evolve the 'genome' by mutating (slightly changing) its parts.
- 4 Accept or reject new tree topologies from a pool of suggested trees according to their likelihood.
- 5 Iterate (3) and (4)



- Start with some (random) tree.
- Start a '*hot chain*' to suggest tree topologies (being far away).
- Accept proposals according to their likelihood.
- Cool down the chain, until the suggestions end up in some (local) optimum.

# How reliable is the reconstructed tree:

- Usually programs deliver a single tree, but without confidence values for the subtrees.
- How can we assess reliability for the subtree?

The Quartet Puzzling algorithm implemented in the TREE-PUZZLE program is a three step procedure:

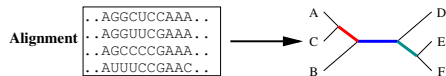
**maximum-likelihood step:** compute ML trees for all quartets of an alignment.

**puzzling step:** compose intermediate tree from quartet trees (this is done multiple times).

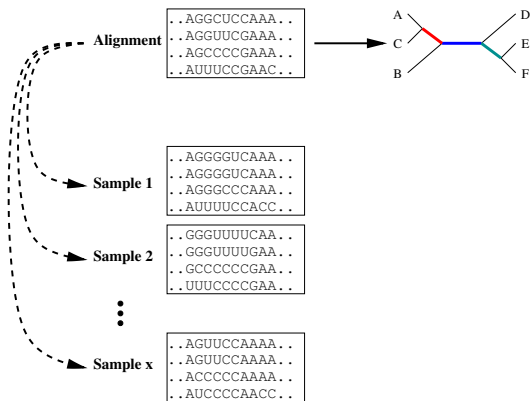
**consensus step:** construct a majority rule consensus tree from the intermediate trees and evaluate the branch lengths.

- We can now reconstruct ML trees, but how comparable are the likelihoods, how reliable the groupings?
- Branch reliability can be checked, support values computed using:
  - Randomizing input orders in stepwise insertions (TREE-PUZZLE).
  - Jackknifing alignment columns + consensus.
  - Bootstrapping alignment columns + consensus.
  - Trees from Bayesian MCMC sampling + consensus.

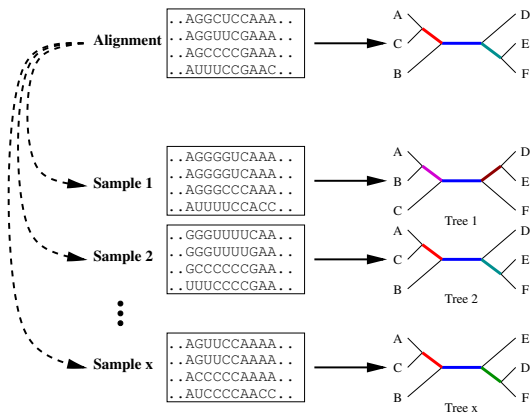
# Estimating Confidence: The Bootstrap



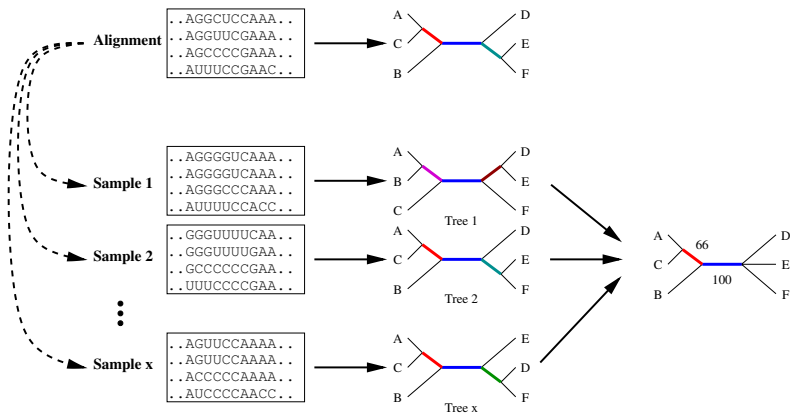
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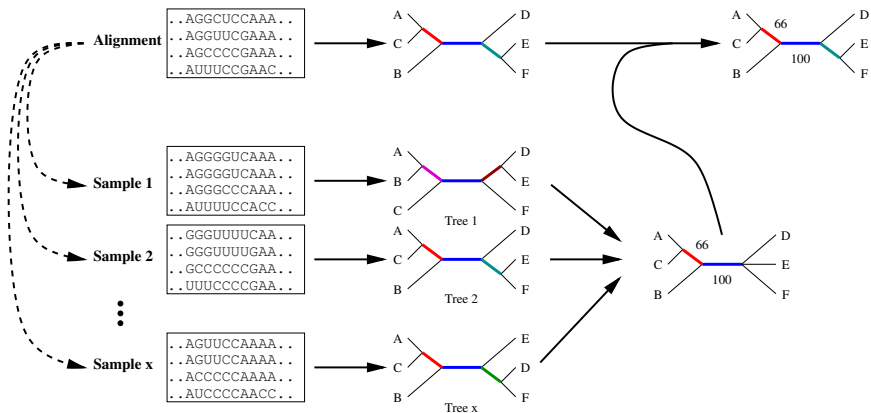


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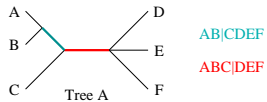




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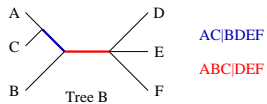


# Summarizing Trees: Consensus Methods



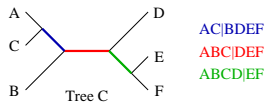
AB|CDEF

ABC|DEF



AC|BDEF

ABC|DEF

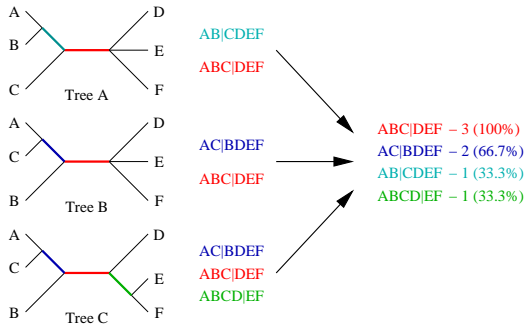


AC|BDEF

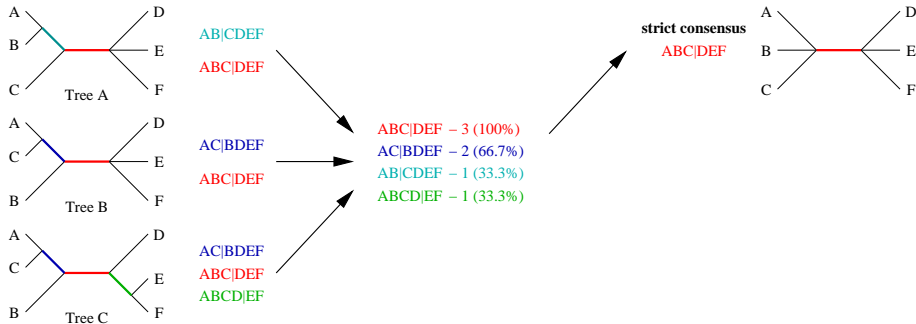
ABC|DEF

ABCD|EF

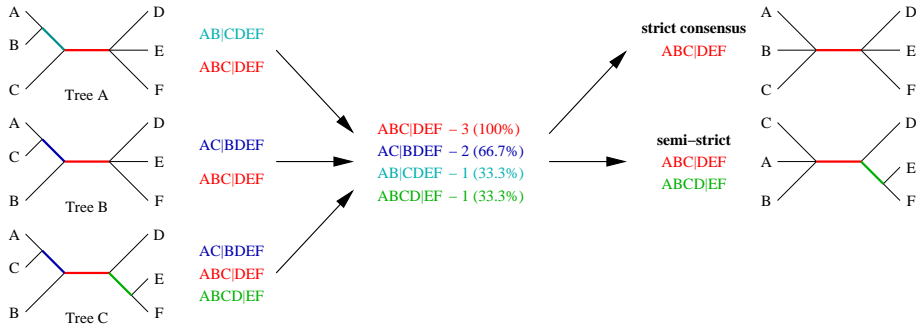
# Summarizing Trees: Consensus Methods



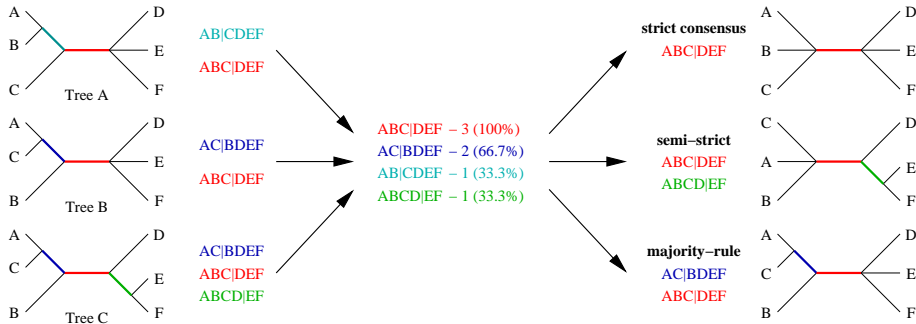
# Summarizing Trees: Consensus Methods



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# Overview over Likelihood-based Analyses

- Comparing hypothesis with Likelihood-Ratio-Test (=LRT)
  - different models of evolution (ModelTest)
  - testing molecular clock assumption and root position (TREE-PUZZLE)
- Parameter estimation (TREE-PUZZLE, PAUP, ModelTest, ...)
- Testing for phylogenetic content (TREE-PUZZLE)
- Comparing/testing different tree topologies with Kishino-Hasegawa test, Shimodaira-Hasegawa test (TREE-PUZZLE), SOWH-test, ELW
- Constructing confidence sets on posterior likelihoods (MrBayes)

- Problem: How different are likelihoods? Just from the value of likelihoods one often cannot tell whether they are significantly different.



# Posterior Probabilities and Empirical Bayes

- Problem: How different are likelihoods? Just from the value of likelihoods one often cannot tell whether they are significantly different.
- Normalization: Posterior probabilities are computed:

$$p_i = \frac{L_1}{\sum_n L_n}$$

- Usage:
  - Which sites along an alignment support a tree most?
  - Are there sites/partitions not supporting a tree?
  - Which model of evolution (e.g. dependent, independent) is supported by which site/partition? (PAML)
  - Is a site fast/medium/slowly evolving? (PAML, TREE-PUZZLE)
  - Constructing confidence sets on posterior tree likelihoods (MrBayes)

# LRT – Likelihood Ratio Test (1)

The Likelihood function offers a natural way of comparing nested evolutionary hypothesis using the **Likelihood Ratio** (LR) statistics:

$$\Delta = 2(\ln L_1 - \ln L_0)$$

$L_1$  maximum likelihood under the **more parameter-rich, complex model**  
(alternative hypothesis,  $H_A$ )

$L_0$  maximum likelihood under the **less parameter-rich simple model**  
(Null-hypothesis,  $H_0$ )

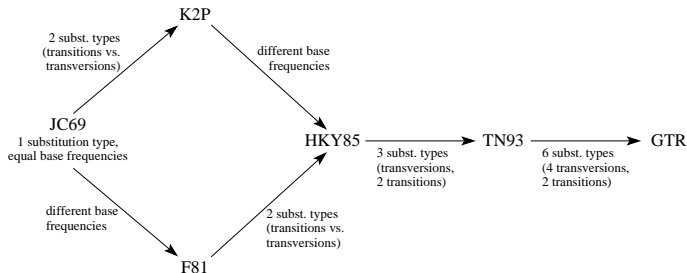
If the models are nested, i.e.,  $H_0$  is a special case of  $H_A$  and the Null-hypothesis ( $H_0$ ) is correct,  $\Delta$  is asymptotically  **$\chi^2$ -distributed** with the number of **degrees of freedom** equal to the difference in number of free parameters between the two models.

## LRT – Likelihood Ratio Test (2)

- If the **LRT is significant** (i.e.,  $p < 0.05$  or  $p < 0.01$ ): the use of the additional parameters in the alternative model  $H_A$  increases the likelihood significantly.
- If  $\Delta$  is **close to zero**, that is,  $p > 0.05$ : the alternative hypothesis  $H_A$  does not fit the data significantly better than  $H_0$ , that means using the additional parameters of  $H_A$  does not explain the data better.
- **Only nested models** can be tested:  
One model ( $H_0$ , Null-model, constraint model) is nested in another model ( $H_A$ , alternative, unconstraint model) if the model  $H_0$  can be produced by restricting parameters in model  $H_A$ .

# LRT – Typical cases of nested models

- Different levels of evolutionary models:



- *rate-homogeneous models* ( $H_0$ ) are nested in *rate-heterogeneous models* ( $H_A$ )
- A tree assuming *molecular clock* ( $H_0$ ) are nested its *non-clock* version ( $H_A$ )

# Exercises:

the exercises can be found at

<http://www.cibiv.at/~hschmidt/VEME/ML>